São Paulo, 14th November 2003

To Whom It May Concern:

We hereby certify that the following papers were presented at the COBEM 2003:

Session MAC03 – ROBOTICS III
Chair: Max Suell Dutra
Co-chair: João Maurício Rosário

1283 Development Of Simulator Of Robotics Manipulators Using Java And VRML
Authors: Cunha Cruz, Victor Cesar Vargas da Silveira; Paula, Aline Souza de; Dutra, Max
Presented by: Aline Souza de Paula

1181 Reconfigurable Architecture Proposal Applied To Mobile Robots
Authors: Rosario, João Mauricio; Erig Lima, Carlos Raimundo
Presented by: João Mauricio Rosario

0276 Improving The Positioning Accuracy Of Robotic Manipulators Subject To Base Oscillations
Authors: Sujan, Vivek Anand; Meggiolaro, Marco Antonio
Presented by: Marco Antonio Meggiolaro

0283 An Optimal Design Of The 3r Manipulators Taking Into Account Regular Workspace Boundary
Authors: Saramago, Sezimária Pereira; Bergamaschi, Paulo Roberto; Nogueira, Antônio Carlos
Presented by: Paulo Roberto Bergamaschi

Prof. Dr. Paulo Eigi Miyagi
Organizing Committee - COBEM2003